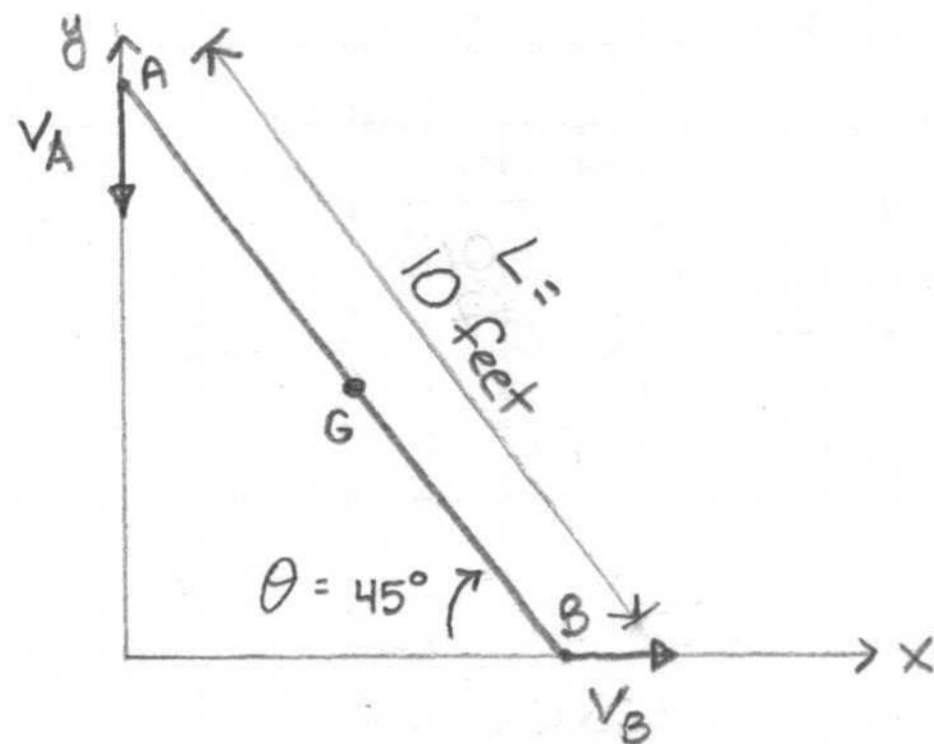


14.2



Given $v_y = 1 \text{ ft/s}$

We know $\vec{v}_G = \vec{v}_A + \vec{\omega} \times \vec{r}_{G/A}$

$$\hookrightarrow \vec{v}_A = -1 \text{ ft/s } \hat{j}$$

$$\vec{\omega} = \omega \hat{k}$$

$$\vec{r}_{G/A} = \frac{L}{2} (\sin \theta \hat{i} - \cos \theta \hat{j})$$

To find $\vec{\omega}$, we know $\vec{v}_B = \vec{v}_A + \omega \hat{k} \times \vec{r}_{B/A}$,
where $\vec{r}_{B/A} = L (\sin \theta \hat{i} - \cos \theta \hat{j})$, $\vec{v}_B = v_B \hat{i}$

$$\therefore v_B \hat{i} = -1 \text{ ft/s } \hat{j} + \omega L (\hat{k} \times \sin \theta \hat{i} + \hat{k} \times -\cos \theta \hat{j})$$

$$v_B \hat{i} = -1 \text{ ft/s } \hat{j} + \omega L (\sin \theta \hat{j} + \cos \theta \hat{i})$$

$$\{ \} \cdot \hat{j} \rightarrow 0 = -1 \text{ ft/s} + \omega L \sin \theta \quad \therefore \omega = \frac{-1}{L \sin \theta}$$

$$\vec{v}_G = -1 \text{ ft/s } \hat{j} + \frac{1}{L \sin \theta} \hat{k} \times \frac{L}{2} (\sin \theta \hat{i} - \cos \theta \hat{j})$$

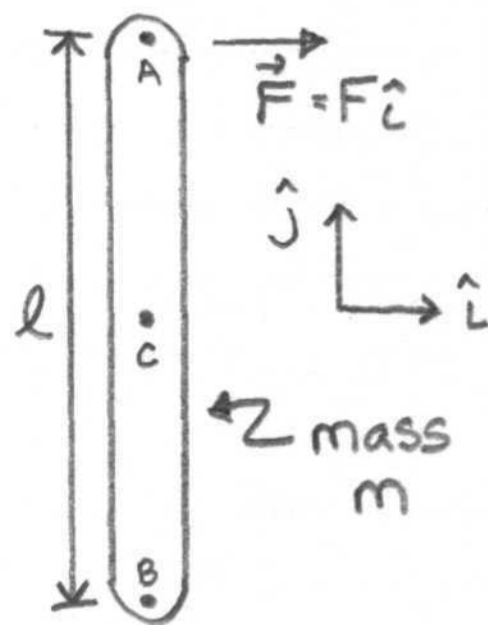
$$= -1 \text{ ft/s } \hat{j} + \frac{1}{2 \sin \theta} [\sin \theta \hat{j} + \cos \theta \hat{i}]$$

$$= -1 \text{ ft/s } \hat{j} + \frac{1}{2} \hat{j} + \frac{1}{2} \cot \theta \hat{i} \quad @ \theta = 45^\circ$$

$$\therefore \boxed{\vec{v}_G = 0.5 \text{ ft/s } \hat{i} - 0.5 \text{ ft/s } \hat{j}}$$

$$\therefore \text{Speed} = \|\vec{v}_G\| = \sqrt{0.5^2 + 0.5^2} = \boxed{0.707 \text{ ft/s}}$$

14.11



$$a) \quad \Sigma \vec{F} = m \vec{a}_c \quad \text{or} \quad F \hat{i} = m \vec{a}_c = m a_c \hat{i}$$

$$\{ \} \cdot \hat{i} \rightarrow F = m a_c$$

$$\therefore \boxed{a_c = F/m}$$

$$b) \quad \Sigma \vec{M}_c = \dot{\vec{H}}_c = I_{zz}^c \dot{\vec{\omega}}_c = \frac{1}{12} m l^2 \dot{\omega} \hat{k}$$

$$\rightarrow \frac{l}{2} \hat{j} \times F \hat{i} = \frac{1}{12} m l^2 \dot{\omega} \hat{k}$$

$$-\frac{F l}{2} \hat{k} = \frac{1}{12} m l^2 \dot{\omega} \hat{k}, \quad \{ \} \cdot \hat{k} \rightarrow -\frac{F}{2} = \frac{1}{12} m l \dot{\omega}$$

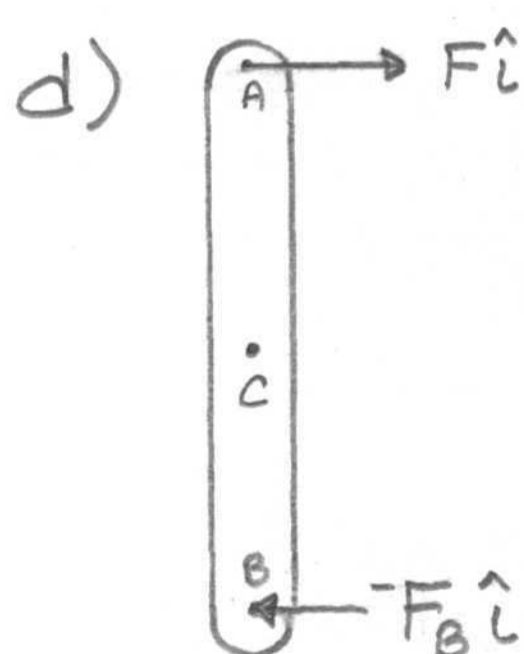
$$\therefore \boxed{\alpha = -\frac{6F}{m l}}$$

$$c) \quad \vec{a}_A = \vec{a}_c + \vec{a}_{A/c} = \vec{a}_c + \dot{\vec{\omega}} \times \vec{r}_{A/c} - \omega^2 \vec{r}_{A/c}, \quad \text{where } \omega = 0 \text{ initially}$$

$$\therefore \vec{a}_A = \vec{a}_c + \dot{\vec{\omega}} \times \vec{r}_{A/c}$$

$$= \frac{F}{m} \hat{i} - \frac{6F}{m l} \hat{k} \times \left(\frac{l}{2} \hat{j} \right) = \frac{F}{m} \hat{i} + \frac{3F}{m} \hat{i}$$

$$\{ \} \cdot \hat{i} \rightarrow \boxed{a_A = 4F/m}$$



$$\Sigma \vec{F} = F \hat{i} - F_B \hat{i} = m \vec{a}_c \quad \therefore \vec{a}_c = \frac{F - F_B}{m} \hat{i}$$

$$(\Sigma \vec{M}_c = \dot{\vec{H}}_c = \frac{1}{12} m l^2 \dot{\omega} \hat{k}) \cdot \hat{k}$$

$$\rightarrow -\frac{l}{2} (F + F_B) = \frac{1}{12} m l^2 \dot{\omega} \quad \therefore \dot{\omega} = \frac{-6}{m l} (F + F_B)$$

$$\vec{a}_B = \vec{a}_c + \vec{a}_{B/c} = \vec{a}_c + \dot{\vec{\omega}} \times \vec{r}_{B/c}$$

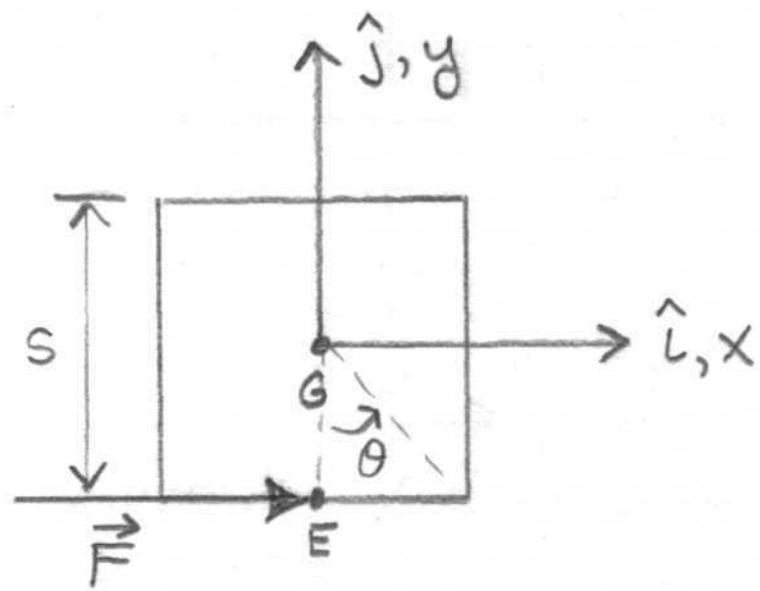
$$= \frac{F - F_B}{m} \hat{i} - \frac{6}{m l} (F + F_B) \hat{k} \times \left(-\frac{l}{2} \hat{j} \right)$$

$$= \frac{F - F_B}{m} \hat{i} - \frac{3}{m} (F + F_B) \hat{i} = 0 \hat{i}$$

$$\{ \} \cdot \hat{i} \rightarrow F - F_B - 3(F + F_B) = 0 = F - 3F - F_B - 3F_B = -2F - 4F_B$$

$$\therefore \boxed{\vec{F}_B = -\frac{F}{2} \hat{i}}$$

14.15



$$\vec{F} = 1 \text{ N } \hat{i}$$

$$m = 1 \text{ kg}$$

$$s = 1 \text{ m}$$

$$a) \{ \sum \vec{F} = 1 \text{ N } \hat{i} = m a_G \hat{i} \} \cdot \hat{i}$$

$$\therefore a_G = 1 \text{ N} / 1 \text{ kg} = 1 \text{ m/s}^2$$

$$\ddot{x}_G = 1 \text{ m/s}^2 \rightarrow \dot{x} = 1 \text{ m/s} t + \dot{x}_0$$

$$\rightarrow x = 1 \text{ m} t^2 / 2 + \dot{x}_0 t + x_0,$$

$$\text{where } \dot{x}_0 = x_0 = 0$$

$$\therefore \boxed{x_G(t) = 0.5 \text{ m} \times t^2}$$

$$b) \sum \vec{M}_G = \dot{H}_G \rightarrow \vec{r}_{E/G} \times \vec{F} = I_{zz}^G \dot{\omega}_c$$

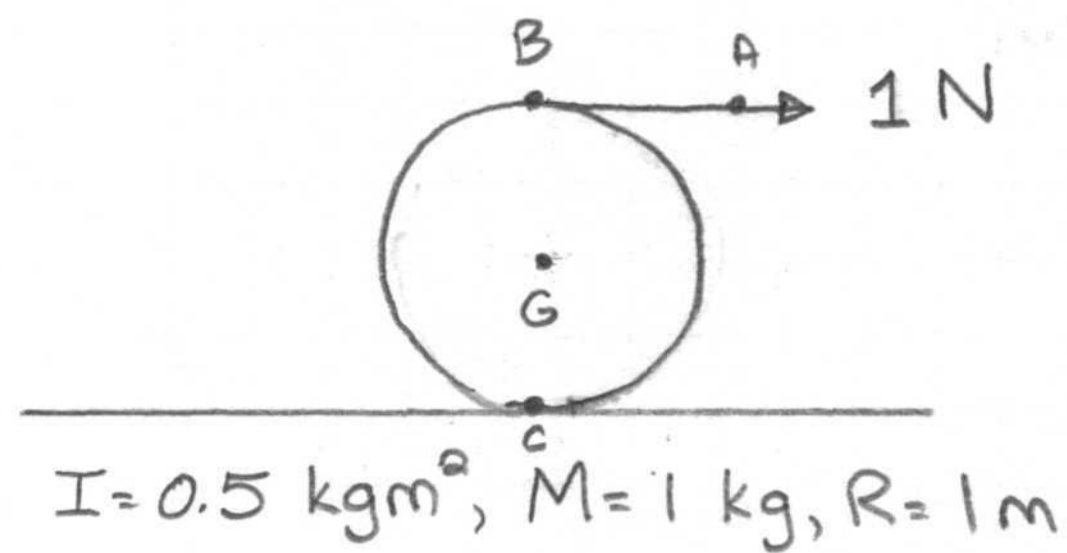
$$\therefore \frac{s}{2} (\sin \theta \hat{i} - \cos \theta \hat{j}) \times (1 \text{ N } \hat{i}) = \frac{1}{12} (2s^2 m) \dot{\omega} \hat{k}$$

$$\text{OR } \frac{s}{2} (1 \text{ N}) (-\cos \theta) (\hat{j} \times \hat{i}) = \frac{1}{6} m s^2 \dot{\omega} \hat{k}$$

$$0.5 \text{ Nm } \cos \theta \hat{k} = \frac{1}{6} (1 \text{ kg}) (1 \text{ m})^2 \dot{\omega} \hat{k}$$

$$\sum \ddot{\theta} \cdot \hat{k} \rightarrow \boxed{\ddot{\theta} - 3 [\text{s}^{-2}] \cos \theta = 0}$$

14.33



$$a) \quad \sum \vec{M}_c = \dot{\vec{H}}_c \quad \text{or} \quad \vec{r}_{B/c} \times \vec{F} = \vec{r}_{B/c} \times m\vec{a}_G + I^G \dot{\omega} \hat{k},$$

where $\vec{a}_G = -\ddot{\theta} R \hat{i}$

$$\therefore (2\hat{j}) \times (1\text{N}\hat{i}) = (2\hat{j}) \times (-m\ddot{\theta}R\hat{i}) - I^G \ddot{\theta} \hat{k}$$

$$-2\hat{k} \text{ [Nm]} = 2m\ddot{\theta}R\hat{k} - I^G \ddot{\theta} \hat{k}$$

$$\{ \} \cdot \hat{k} \rightarrow -2 \text{ Nm} = [(2m)mR - I^G] \ddot{\theta}$$

$$\therefore \ddot{\theta} = \frac{-2 \text{ Nm}}{2m(1\text{kg})(1\text{m}) - 0.5 \text{ kgm}^2} = \boxed{-4/3 \text{ rad/s}^2}$$

$$b) \quad \vec{a}_B = \vec{a}_G + \vec{a}_{B/G} = \vec{a}_G + \vec{r} \times \vec{\alpha}$$

$$= -\ddot{\theta} R \hat{i} + (R\hat{j}) \times (-\ddot{\theta} \hat{k})$$

$$= -\ddot{\theta} R \hat{i} - \ddot{\theta} R \hat{i} = -2\ddot{\theta} R \hat{i}$$

$$a_A = a_B = -2\ddot{\theta} R = 2(4/3 \text{ rad/s}^2)(1\text{m}) = \boxed{8/3 \text{ m/s}^2}$$